

Series 18

Intrinsically Safe Pulse frequency output Shaft Rotation Speed Sensors

USERS MANUAL



Description

Series 18 sensors detect passing magnets from a shaft-mounted pulser target and output a square-wave pulse signal with frequency proportional to the shaft rotation speed.

All models operate down to (and including) zero speed.

Signal, output and termination options provide speed or speed + direction signaling and compatibility with plc inputs, tachometers, data acquisition modules and various frequency meters.

Options include four stainless-steel M18x1 housings, Hall-effect and Magnetoresistive sensing, single or quadrature signaling and NPN (sinking) or PNP (sourcing) transistor outputs (open-collector or terminated). All models operate from standard 24Vdc.

All models are factory filled and sealed against entrance of liquids and dust.

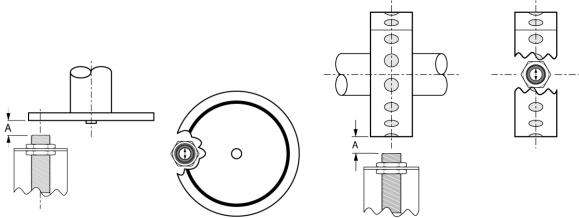
All models come standard with a mounting bracket and two stainless steel hex jam nuts.

Installation Gap/Allignment

Mount the pulser target (disc or wrap) to the shaft.

Mount the sensor as shown. Adjust the gap (A) per the model specification.

For quadrature models, align the arrow label with the center path of the pulser target magnets as shown.



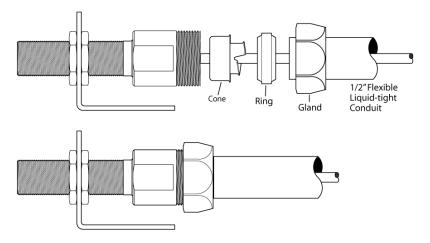
With pulser disc (18*HQ** shown)

With pulser wrap (18*HQ** shown)

Installation 18F****

Assemble ½ in flexible liquid-tight conduit into 18F models as shown.

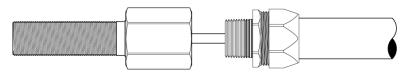
Slide the gland and ring over the end of the conduit and screw the cone into (and over) the end of the conduit. Install the conduit over the cable and secure it to the sensor housing by tightening the gland enough to seal – do not over-tighten.



Installation 18R****

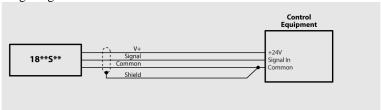
Assemble conduit and fitting into 18R models as shown.

To obtain a watertight seal, use teflon tape or suitable pipe dope sealant on the ½ NPT side of the fitting. Tighten enough to seal.

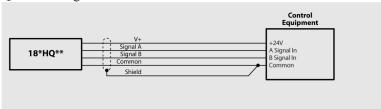


Wiring (non-I.S.)

Single signal



Quadrature signal



Notes:

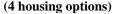
Connect the cable shield to signal input common at the receiving equipment only.

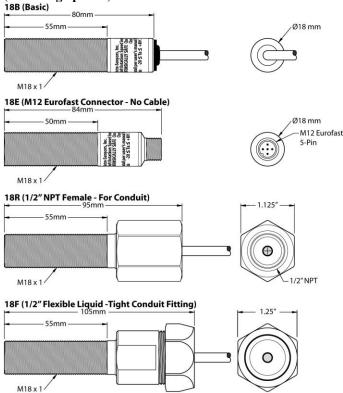
Do not connect the cable shield to earth or chassis ground; leave the signal input common floating. For open-collector models ($18^{***}O$), a minimum $2.4k\Omega$ termination resistance is required on each signal, preferably located at the control equipment signal input(s): Signal In to Common (pull-down) for $18^{***}P^*$, Signal In to +V (pull-up) for $18^{***}N^*$; external or internal.

Wiring (I.S.)

I.S. installations must be wired per the Series 18 I.S. Control Drawing 990-006100.

Dimensions





Output Functions

$$f_{pulse}(Hz) = RPM * PPR / 60$$

$$RPM = f_{pulse}(Hz) * 60 / PPR$$

K

RPM is the shaft revolutions-per-minute.

PPR is the number of signal pulses per pulser target (shaft) revolution – for the pulser target and sensor used. PPR (18*H***, Hall-Effect sensing) = number of pulser N-S magnet pairs (1/2 the pulser target magnets).

PPR (18*MS**, Magnetoresistive sensing) = number of pulser target magnets.

Magnetoresistive (18*MS**) gives 2X the PPR and frequency of Hall-Effect (18*H***).

Some pulser target restrictions exist for Magnetoresistive (18*MS**) - consult factory.

Note:

Model number **-W**: wide-temp option (otherwise blank, available for 18B/R/F only) 18 Cable length, ft (18B/R/F only, use leading zeros; 18E blank) – 010 is standard O: open-collector (un-terminated) output(s) LT: terminated output(s) (internal 10kΩ: pull-up for 18***NT, pull-down for 18***PT) N: NPN (sinking) output(s) • **P**: PNP (sourcing) output(s) **S**: single signal: speed only Q:quadrature signal (Signal A, Signal B; 18*HQ** only): speed and direction **H**: Hall-Effect sensing (one signal pulse per pulser target N-S magnet pair) LM: Magnetoresistive sensing (one signal pulse per pulser target magnet) **B**: M18x1 housing (Basic) · E: M18x1 housing with 5-pin male M12 (Eurofast) connector – no cable - R: M18x1 housing with ½ NPT female conduit port F: M18x1 housing with ½ in (Flexible) liquid-tight conduit fitting Examples: 18BHSNO-010 Basic housing, Hall-effect sensing, single signal, NPN output, open-collector, 10ft cable (standard length), standard temp (not wide-temp) 18EHQPT M12 (Eurofast) connector, Hall-effect sensing, quadrature signal, PNP outputs, terminated (internal $10k\Omega$ pull-down resistors) Flexible liquid-tight conduit fitting, Magnetoresistive sensing, single signal, PNP 18FMSPO-025-W output, open-collector, 25ft cable, wide-temp Cable (18B/R/F****) Type UL 2464, shielded, 3 or 4 conductor, 24 AWG (all 18B/R/F without -W option) Teflon jacket, shielded, 3 or 4 conductor, 22 AWG (all 18B/R/F with -W option) Conductors Red V+Black Common White Signal (18**S**-***), Signal A (18*HQ**-***) Signal B (18*HQ**-*** only) Green Connector/pin-out (18E****) M12 male, 5-pin (mates with M12 female on cord-set) 1

unconnected

2 V+

3 Common

Signal (18E*S**), Signal A (18EHQ**) 4

5 Signal B (18EHQ** only, else unconnected)

Specifications Sensor Gap 1/4 in $\pm 1/8$ in (using pulser targets with $\frac{1}{2}$ " magnets)

> $10 \rightarrow 26 \text{ Vdc}$ V+

I (V+) (no Signal load) 10 mA max (18****O)

I (Signal or Signal A/B) 10 mA max (NPN sink / PNP source) – each output Ro (18****T only) 10 k Ω Signal to V+ (18***NT), Signal to Common (18***PT)

Operating Temp $-40 \rightarrow +100 \,^{\circ}\text{C} \, (-40 \rightarrow 212 \,^{\circ}\text{F})$ (18*****-W only)

 $-30 \rightarrow +80 \,^{\circ}\text{C} \, (-22 \rightarrow 176 \,^{\circ}\text{F})$ (18E**** only)

> $-20 \rightarrow +80 \,^{\circ}\text{C} \, (-4 \rightarrow 176 \,^{\circ}\text{F})$ (all others)

Frequency (f_{pulse}) $0 \to 20,000 \text{ Hz}$

Approvals/ Intrinsically Safe Class I Div 1 (A, B, C, D), Class 2 Div 1 (E, F, G); AEx[ia] IIC **Ratings**

Install for I.S. per the Series 18 I.S. Control Drawing 990-006100

(18B****-***-W, 18R****-***-W, 18F****-***-W) T4 $Ta \le 100 \, ^{\circ}C$

T5 $Ta \le 80 \, ^{\circ}C$ (all others)

(all 18R****-*** and 18F****-***) IP65 4X



