

# ION – Analog Input Modbus RTU Node USERS MANUAL



6111 Blue Circle Drive Minnetonka, MN 55343 Phone: 952-930-0100 Fax: 952-930-0130 ISO 9001:2000 Certified



Free Catalog and Application Assistance **1-800-328-6170** Visit us online www.electro-sensors.com **990-005200 Rev B** 

## Description

The ION Analog Input Modbus RTU Node is a 24Vdc powered, DIN rail mountable industrial data acquisition device with twelve 0/4-20mA signal inputs (In1  $\rightarrow$  In12), six sensor power outputs and a Modbus RTU/RS485 slave interface. The twelve analog input signal levels are continuously and independently measured and available for access over Modbus.

### Installation/Mounting

Attaching to DIN rail

Orient the unit vertically with the LED LENS on the LEFT and the ROTARY SWITCHES (located behind the removable front cover) on the RIGHT (see Figure 1).

Slide the rear clip bottom groove onto the DIN rail bottom edge (rear clip springs should be pointing up and behind the rail bottom edge).

While pushing UP on the unit (compressing the rear clip springs), push the unit BACK until the rear clip top clears the rail top edge and snaps into place.

#### Detaching from DIN rail

Push the unit UP (compressing the rear clip springs) until the clip top can tilt free from the DIN rail top edge, tilt the unit top slightly forward enough to free it. Be careful not tilt too much (the rear clip springs can break). Now lower the unit to free it from the rail bottom edge.



Figure 1

Terminal blocks (see Figure 1)

Sensor connection terminals are organized into 6 pluggable 4-terminal blocks (TB1 ... TB6), each with: 1 Sensor DC power output terminal (+Vs)

2 Sensor signal input terminals (In)

1 Signal common terminal (COMs)

Modbus RTU/RS485 terminals are located on 1 pluggable 4-terminal block (TB7 – lower left) with:

1 unused terminal (N.C.)

1 D1 (+) terminal (EIA/TIA-485 B)

1 D0 (-) terminal (EIA/TIA-485 A)

1 COMc common terminal (EIA/TIA-485 C)

24Vdc Power In terminals are located on 1 pluggable 4-terminal block (TB8 – lower right) with:

1 Vp(+) terminal to connect to external power supply + (+24Vdc, red)

2 unused terminals (N.C.)

1 Vp(-) terminal to connect to external power supply – (Common, blk)

#### Wiring sensors to inputs (see Figure 1 and Figure 2)

Connect sensors to Vs, In and COMs terminals within the SAME TERMINAL BLOCK (as shown in Figure 2). Notes:

Each Vs terminal provides enough power for two "2-wire" (+ and -) 4-20mA devices.

Each Vs terminal provides enough power for one "3-wire" (V+, signal and common) 4-20mA device only. When powering a 3-wire device from Vs, no other sensor should be connected to that same terminal block.





## Setting the rotary switches (see Figure 1)

Three rotary switches (two slave Address, one Baud/Parity) are located under the removable front cover. Remove the front cover by prying it free at the indented pry points (re-attach it after switches are set). Set the slave Address switches to a UNIQUE value (in range  $01 \rightarrow 99$ ; do not set to 00) within the Modbus network.

Set the Baud/Parity switch for the SAME baud rate, parity and stop bit setting as ALL other devices on the network. Serial Baud/Parity switch

Setting	Baud rate	Data bits	Parity / Stop bits
0	9.6k	8	None / 2
1	19.2k	8	None / 2
2	38.4k	8	None / 2
3	57.6k	8	None / 2
4	115.2k	8	None / 2
5	9.6k	8	Even / 1
6	19.2k	8	Even / 1
7	38.4k	8	Even / 1
8	57.6k	8	Even / 1
9	115.2k	8	Even / 1

Table 1

In Figure 1 the Address is 64 and the Baud / Data / Parity / Stop settings are <u>38.4k / 8 / None / 2</u>. Note:

## **Supported Modbus function codes**

- Read Holding Registers (4XXXX) 03
- 04 Read Input Registers (3XXXX)

#### Sensor signal data

Each input has a dedicated 16-bit Modbus Input Register and Holding Register for reading its signal data. For any analog input, the corresponding 16-bit input and holding register values are the same.

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	Analog Input	Input Register	Holding Register	Data Range $(0 \rightarrow 20.800 \text{mA input})$	
	In1	30001	40001	$0 \rightarrow 20800 (1 \text{ count/}\mu\text{A})$	
	In2	30002	40002	$0 \rightarrow 20800 (1 \text{ count/}\mu\text{A})$	
	In3	30003	40003	$0 \rightarrow 20800 (1 \text{ count/}\mu\text{A})$	
	In4	30004	40004	$0 \rightarrow 20800 (1 \text{ count/}\mu\text{A})$	
	In5	30005	40005	$0 \rightarrow 20800 (1 \text{ count/}\mu\text{A})$	
	In6	30006	40006	$0 \rightarrow 20800 (1 \text{ count/}\mu\text{A})$	
	In7	30007	40007	$0 \rightarrow 20800 (1 \text{ count/}\mu\text{A})$	
	In8	30008	40008	$0 \rightarrow 20800 (1 \text{ count/}\mu\text{A})$	
	In9	30009	40009	$0 \rightarrow 20800 (1 \text{ count/}\mu\text{A})$	
	In10	30010	40010	$0 \rightarrow 20800 (1 \text{ count/}\mu\text{A})$	
	In11	30011	40011	$0 \rightarrow 20800 (1 \text{ count/}\mu\text{A})$	
	In12	30012	40012	$0 \rightarrow 20800 (1 \text{ count/}\mu\text{A})$	

Signal over-range (current exceeding 20.8mA) is indicated by 65,535 (0xFFFF) Note:

LED operation				
Power/Device status (green) Communication (yellow) Error (red)	ON: ON: ON: Flashing:	Device is powered Device is polled by a Modbus master at least once per second. Fault (signal over-range) Communications fault (e.g. incorrect slave address, baud rate,		
		message length; CRC or character error)		
Specifications DC Power input (TB8) Vp (Vp(+) – Vp(-))	24Vdc ±5%			
I NOTE	300mA (max) Apply 24Vdc p DO NOT apply	- sensor DC power outputs (+Vs) fully loaded (40 mA each) ower across the TB8 Vp(+) and Vp(-) terminals. See Figure 1. power to Modbus RTU/RS485 terminals.		
Sensor DC power outputs (+Vs)				
V I	Vp – 1V 40mA (max): Each +Vs outpu power when ov from that termin	each Vs terminal can supply two 2-wire 4-20mA sensors. It terminal is protected by an internal device which shuts off erloaded. To reset a +Vs terminal's power, remove ALL load hal and wait 1 minute.		
Signal current inputs (In1 In12)				
Range Rin	$0 \rightarrow 20.8 \text{mA} \text{ (r}$ 510 $\Omega$	neasurable)		
Signal current measurement Resolution Accuracy Range Conversion rate (each input)	1 $\mu$ A (1 count per $\mu$ A: e.g. codes 4,000 $\rightarrow$ 20,000 indicate 4.000 $\rightarrow$ 20.000 mA) $\pm 0.1\% \pm 1$ count (1 $\mu$ A) max error0 $\rightarrow$ 20,800 (normal range codes for 0.000 $\rightarrow$ 20.800 mA)65,535 (0xFFF) (OVER-RANGE code for current > 20,800 mA)600 mS (12 input signals are sequentially converted, 1 every 50 mS)			
RS485 serial port (TB7)				
Isolation voltage Differential output voltage Configuration Baud/Parity/Stop-bits NOTES	1kV (min) 1.5V (min) @ 5 2-wire RS485 (see Table 1) se Connect the TE D1(+), D0(-) ar DO NOT connect	4Ω line impedance t with 1 rotary Baud/Parity switch (see Figure 1) 7 terminals to a half-duplex "2-wire" configured RS485 network: d COMc terminals - see p. 2 Terminal Blocks and Fig 1. ect power sources to TB7 terminals or the RS485 network.		
Modbus RTU slave				
Query → response latency Slave address Supported function codes Supported data addresses	1 mS (max) - m $(01 \rightarrow 99) \text{ set d}$ See Supported 2 See Sensor sign	aster query message end to ION response message start irectly with 2 rotary Address switches (see Figure 1) Modbus function codes al data		
Electrical isolation/grounding	3 isolated electron The sensors and	onic circuits: sensors/power, internal digital and RS485 port. 1 24Vdc power input (Vp) share the same circuit.		
Operating temperature	$-40 \rightarrow +185^{\circ}\text{F} (-40 \rightarrow +85^{\circ}\text{C})$			
Dimensions	4.65 in (118 mr	n) H, 1.77 in (45 mm) W, 4.88 in (124 mm) D		

Weight 0.50 Lb (0.23 kg)