## PU 210

## Level Converter, Potential Separator and Direction Signal Decoder for Incremental Encoder Signals



- Signal inputs $A, B, Z$ and $/ A, / B, / Z$, adjustable to either RS422 format or TTL level or HTL (10-30V) level
- Signal outputs A, B, Z and /A, /B, /Z, likewise adjustable to either RS422 format or TTL level or HTL (10-30V) level
- Potential separation between input and output
- Conversion of a $\mathrm{A} / \mathrm{B}$ quadrature direction signal to a static direction output and vice-versa
- Encoder connection alternatively via Sub-D-connectors or parallel screw terminal strips


## Operating Instructions

## 今 <br> Safety Instructions

- This manual is an essential part of the unit and contains important hints about function, correct handling and commissioning. Non-observance can result in damage to the unit or the machine or even in injury to persons using the equipment!
- The unit must only be installed, connected and activated by a qualified electrician
- It is a must to observe all general and also all country-specific and applicationspecific safety standards
- When this unit is used with applications where failure or maloperation could cause damage to a machine or hazard to the operating staff, it is indispensable to meet effective precautions in order to avoid such consequences
- Regarding installation, wiring, environmental conditions, screening of cables and earthing, you must follow the general standards of industrial automation industry
-     - Errors and omissions excepted -

| Version: | Description: |
| :--- | :--- |
| PU21001d/af/hk/Aug.05 | Original Edition |
| PU21001d/af/hk/Feb.06 | Edition A5 GER/ENG/FRA |
| PU21002a/kk/hk/Feb.08 | Corrections: HTL output level, switch assignments A/B/Z |
| PU21003a/af/hk/Feb.11 | Supplement: processing of single-ended TTL signals |

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## 1. Introduction

This universal level converter, on the input side, can accept single channel and quadrature encoder signals with either RS422 format or TTL level or HTL (10-30V) level. Where the signal provides direction information, the direction may be defined by either an $\mathrm{A} / \mathrm{B}-90^{\circ}$ phase displacement, or by a static direction signal.
Independent of the input level and the mode of direction information, the output provides $A, / A, B, / B$ und $Z, / Z$ signals, and again the direction may be selected as quadrature $A / B$ format or as a static direction signal. The outputs provide push-pull characteristics and the output level is about 1.5 volts lower than the power supply voltage ( +5 to +30 volts DC ).
Inputs and outputs are isolated via inductive high-speed couplers. All signals can be connected alternatively via Sub-D-connectors or by parallel screw terminal strips.
PU210 uses a slim and space-saving plastic housing for DIN rail mounting.
The subsequent block diagram explains all essential details:


Even with differential operation on the input side it may be advantageous to connect the signal common to GNDin (terminal 9 of X2 or pin 5 of X1).
This may result in better signal quality and will not affect at all the potential separation between input and output

## 2. Construction and Electrical Connections



### 2.1. Power supply

The unit requires a DC supply between 5 and 30 volts.
The level of the supply voltage will at the same time determine the output swing (voltage drop approx. 1.5 volts, i.e. 24 V power supply will result in a 22.5 V output swing)
The supply voltage can either be applied to the screw terminals marked "GND" and "+VIN" on terminal strip X4, or also to the female Sub-D-9 output connector X3, using pin 5 (GND) and pin 4 (+VIN).

### 2.2. Encoder supply

On the input side, pin $4(+)$ and pin $5(-)$ of the Sub-D-connector X 1 can be used for encoder supply, provided that a corresponding supply voltage is applied to the parallel screw terminals V1 and GND1 of terminal strip X2. The unit itself does not provide any internal encoder supply.

### 2.3. Function of the LEDs

The green LED on the front side is to indicate „power on".
The yellow LED indicates directly the input impulses from input channel A.

## 3. Switch settings

The front DIL switches require a few settings depending on the signal levels and the mode of indicating the direction on inputs and outputs

### 3.1. Input characteristics

You can set the desired input characteristics by switch DIL2, positions 6, 7 and 8

| $\begin{aligned} & 0=\mathrm{OFF} \\ & 1=\mathrm{ON} \end{aligned}$ |  |  |  |  |  | DIL2 |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 87 | 6 | 4 | 3 | 2 | 1 |  |
| $\begin{array}{\|r\|r\|r\|} \hline 1 & 1 \\ (Z) & \text { (B) } \end{array}$ | $\begin{gathered} 1 \\ (\mathrm{~A}) \end{gathered}$ |  |  |  |  | Single-ended input: Only signals $A, B$ and $Z$ are connected, the inverted inputs /A, /B, /Z remain unconnected. <br> Acceptable input level: HTL, $10-30 \mathrm{~V}$ *) <br> (PNP only, must switch to +) |
| $\begin{array}{\|c\|c} 0 & 0 \\ (Z) & 0 \\ (B) \end{array}$ | $\left.\left\lvert\, \begin{array}{c} 0 \\ \text { (A) } \end{array}\right.\right)$ |  |  |  |  | Differential input (RS422): with every signal, also the corresponding inverted signal must be connected ( $A, / A, B, / B, Z, / Z$ ). Acceptable input level of differential signals: $3-30$ volts |
|  |  | tting of ove ind ith RS4 fferentia Itage o ngle-en | the in cation 22 set TT 1 volt | as | (B), <br> the $c$ <br> als an <br> equire <br> with | at is separately for each of the encoder channels, according to (Z) corresponding input will accept RS422 signals as well as ald also $10-30 \mathrm{~V}$ HTL levels. However, a minimum differential d. <br> standard applications need HTL level ( $10-30$ volts) *) |

[^0]

With standard applications please never touch the DIL switch hidden behind the front plate!

### 3.2. Output level

The output level depends directly on the power supply level applied to VIN. However, for best edge steepness and short-circuit-proof, switch DIL1, positions 1 to 6 must be set with regard to the level used.

The output always provides the inverted signals, even when these are not available on the input side.


## 3．3．Definition of the direction of rotation

The unit is designed to evaluate quadrature direction information $\left(A / B, 2 \times 90^{\circ}\right)$ and static direction information as well．Furthermore it can convert the direction information from one format to the respective other format．Positions 3， 4 and 5 of switch DIL2 provide individual selection for input and output．

| $\begin{aligned} & 0=\mathrm{OFF} \\ & 1=\mathrm{ON} \end{aligned}$ |  |  |  |  |  |  |  | DIL2 |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 8 | 7 | 6 | 5 | 4 | 3 | 2 | 1 |  |  |
|  |  |  | 0 | 0 | 1 |  |  |  | Output：quadrature direction |
|  |  |  | 0 | 1 | 0 |  |  | Input：quadrature direction | direction $\square \square \square \square \square$ Output：static direction |
|  |  |  | 1 | 0 | 0 |  |  | Output format | $=$ input format |

## 3．4．Phase displacement $\mathrm{A} / \mathrm{B}$

These settings are only relevant with single channel input signals（input A alone or A with B as a static direction information），when this information needs to be converted into a quadrature A／B format at the output．
In this case the unit will generate a time－constant phase displacement＂ T ＂．This displacement can of course correspond to $90^{\circ}$ at a specific frequency only，which however will not be a disadvantage with most of the target units available on the market．
Please select the time of $A / B$ displacement according to the maximum frequency indications given in the setting table．
Displacement times will add up when several positions are switched on at the same time．

| $\begin{aligned} & 0=0 \mathrm{FF} \\ & 1=\mathrm{ON} \end{aligned}$ |  |  |  |  |  |  |  | DIL1 |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 8 | 7 | 6 | 5 | 4 | 3 | 2 | 1 |  |  |
|  | 1 |  |  |  |  |  |  | T＝＋22us（12 kHz） |  |
| 1 |  |  |  |  |  |  |  | $\mathrm{T}=+5 \mathrm{us}(50 \mathrm{kHz}$ ） | Time displacement A／B |


| $\begin{aligned} & 0=0 \mathrm{FF} \\ & 1=\mathrm{ON} \end{aligned}$ |  |  |  |  |  |  |  | DIL2 |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 8 | 7 | 6 | 5 | 4 | 3 | 2 | 1 |  |  |
|  |  |  |  |  |  |  | 1 | $\mathrm{T}=+2.5 \mathrm{us}(100 \mathrm{kHz})$ | Time displacement $\mathrm{A} / \mathrm{B}$ |
|  |  |  |  |  |  | 1 |  | $\mathrm{T}=+1$ us（250 kHz） |  |

## 4. Dimensions and Specifications



| Power Supply Vin | $5-30 \mathrm{~V}$ DC |
| :---: | :---: |
| Current consumption (without load) | 50 mA |
| Max. frequency | 500 kHz (RS422), 300 kHz (HTL) |
| Input | a) Differential RS422 (A, /A, B, /B, Z, /Z), level 3-30 V, (differential voltage min. 1 V ) |
|  | b) Single-ended $A, B, Z$ at HTL level $10-30 \mathrm{~V}$ (Standard application) |
|  | c) Single-ended $A, B, Z$ at TTL level 5 V (special application, needs special DIL switch setting) |
| Output | HTL or TTL, push/pull (A, /A, B, /B, Z, /Z), 5-30V, 30 mA |
| Propagation delay time | approx. 600 ns |
| Temperature range ( ${ }^{\circ} \mathrm{C}$ ) | Operation: $0^{\circ}-45^{\circ} \mathrm{C}\left(32-113^{\circ} \mathrm{F}\right)$ <br> Storage: $-25^{\circ}-+75^{\circ} \mathrm{C}\left(-13-158^{\circ} \mathrm{F}\right)$ |
| Weight | approx. 100 g |
| Conformity and standards | EMC 2004/108/EEC: EN 61000-6-2 |
|  | EN 61000-6-3 |


[^0]:    ${ }^{*}$ ) Where exceptionally single-ended TTL signals have to be processed (i.e. TTL signals with no inverted channels), a special DIL switch hidden behind the front plate provides corresponding setting facilities. To access this switch, please slightly lift up the front plate on its bottom side as shown beside.

